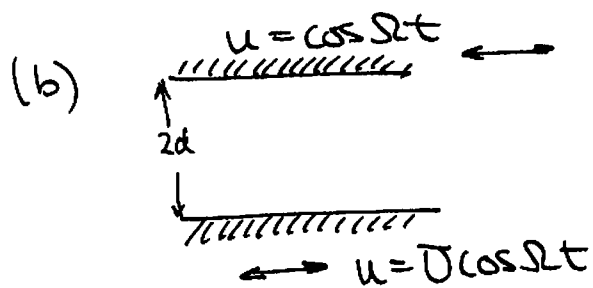


2009

#1 First parts are standard.



Assuming $\underline{u} = [u(y, t), 0]$,
clearly the NS eqns reduce
to:

$$\rho u_t = \mu u_{yy}$$

Now let $u = \Re [U f(y) e^{i\Omega t}] = U f(y) e^{i\Omega t}$

(ignore real parts since problem is linear)

B.C.s $u(\pm d, t) = U \cos \Omega t \Rightarrow$ need $f(\pm d) = 1$

Substituting gives:

$$f'' - \frac{\rho i \Omega}{\mu} f = 0$$

Let $f = e^{ry} \Rightarrow r^2 = \frac{\rho \Omega}{\mu} \cdot i$

$$\Rightarrow r = \pm \sqrt{\frac{\rho \Omega}{2\mu}} (1+i)$$

$\underbrace{\hspace{1cm}}_k$

$$\therefore f(y) = A \cosh k(1+i)y + B \sinh k(1+i)y$$

(much easier form for B.C.s)

$$f(\pm d) = 0 \Rightarrow B = 0 \quad ; \quad A = \frac{1}{\cosh k(1+i)d}$$

As $kd \rightarrow \infty$, $f(y) = \frac{\cosh k(1+i)y}{\cosh k(1+i)d} \sim \frac{2}{e^{k|1+i|d}} \cdot \cosh k(1+i)y$

\uparrow
exp. large.

So u is exp. small, except if $y \sim O(\frac{1}{k})$

#1. a) Prove the transport theorem.

$$\begin{aligned} \frac{d}{dt} \iiint_{V(t)} F(\underline{x}, t) \cdot dV &= \frac{d}{dt} \iiint_{V(0)} F \cdot J \cdot dx_1 dx_2 dx_3 \\ &= \iiint_{V(0)} \frac{D}{Dt} (FJ) \cdot dx_1 dx_2 dx_3 \\ &= \iiint_{V(0)} \left(\frac{DF}{Dt} J + F \frac{DJ}{Dt} \right) dx_1 dx_2 dx_3 \\ &= \iiint_{V(t)} \left(\frac{DF}{Dt} + F \frac{\partial J}{\partial t} \frac{1}{J} \right) dV \end{aligned}$$

now by Euler's Thm,

$$\frac{DJ}{Dt} = J(\nabla \cdot \underline{u})$$

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + (\underline{u} \cdot \nabla)$$

$$= \iiint_{V(t)} \left(\frac{DF}{Dt} + F(\nabla \cdot \underline{u}) \right) dV$$

$$= \iiint_{V(t)} \left(\frac{\partial F}{\partial t} + \nabla \cdot (F\underline{u}) \right) dV$$

□

Prove Euler's Thm: write $J = \epsilon_{ijk} \frac{\partial x_1}{\partial X_i} \frac{\partial x_2}{\partial X_j} \frac{\partial x_3}{\partial X_k}$

$$\frac{DJ}{Dt} = \epsilon_{ijk} \left\{ \frac{\partial}{\partial X_i} \frac{\partial u_1}{\partial x_m} \frac{\partial x_2}{\partial X_j} \frac{\partial x_3}{\partial X_k} + \frac{\partial x_1}{\partial X_i} \frac{\partial u_2}{\partial x_m} \frac{\partial x_3}{\partial X_j} \frac{\partial x_3}{\partial X_k} + \frac{\partial x_1}{\partial X_i} \frac{\partial x_2}{\partial X_j} \frac{\partial u_3}{\partial x_m} \frac{\partial x_m}{\partial X_k} \right\}$$

(chain rule)

$$= \epsilon_{ijk} \left\{ \frac{\partial u_1}{\partial x_m} \frac{\partial x_m}{\partial X_i} \frac{\partial x_2}{\partial X_j} \frac{\partial x_3}{\partial X_k} + \frac{\partial u_2}{\partial x_m} \frac{\partial x_1}{\partial X_i} \frac{\partial x_m}{\partial X_j} \frac{\partial x_3}{\partial X_k} + \frac{\partial u_3}{\partial x_m} \frac{\partial x_1}{\partial X_i} \frac{\partial x_2}{\partial X_j} \frac{\partial x_m}{\partial X_k} \right\}$$

$$= \frac{\partial u_1}{\partial x_m} \frac{\partial (x_m, x_2, x_3)}{\partial (X_i, X_j, X_k)} + \frac{\partial u_2}{\partial x_m} \frac{\partial (x_1, x_m, x_3)}{\partial (X_i, X_j, X_k)} + \frac{\partial u_3}{\partial x_m} \frac{\partial (x_1, x_2, x_m)}{\partial (X_i, X_j, X_k)}$$

$$= \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) J$$

$$= (\nabla \cdot \underline{u}) J$$

□

b) Consv. of mass:

$$\frac{D}{Dt} \iiint_{V(t)} \rho \, dV = \iiint_{V(t)} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) \, dV = 0$$

Incompressible $\Rightarrow \frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + (\mathbf{u} \cdot \nabla) \rho = 0$

$$\therefore \underbrace{\frac{\partial \rho}{\partial t} + (\mathbf{u} \cdot \nabla) \rho}_{=0} + \rho (\nabla \cdot \mathbf{u}) = 0 \Rightarrow \boxed{\nabla \cdot \mathbf{u} = 0}$$

Consev. of momentum:

$$\frac{D}{Dt} \iiint_{V(t)} \rho u_i \, dV = \iiint_{V(t)} \rho g_i \, dV + \iint_{\partial V} \sigma_{ij} n_j \, dS.$$

$$\Rightarrow \frac{\partial (\rho u_i)}{\partial t} + \nabla \cdot (\rho u_i \mathbf{u}) = \rho g_i + \frac{\partial \sigma_{ij}}{\partial x_j}$$

But $\frac{\partial \sigma_{ij}}{\partial x_j} = \frac{\partial}{\partial x_j} \left\{ -p \delta_{ij} + \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right\} = -\frac{\partial p}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$

$\uparrow \qquad \qquad \qquad \uparrow$
 $= 0$ since $\nabla \cdot \mathbf{u} = 0$.

$$\therefore \frac{\partial (\rho u_i)}{\partial t} + \rho u_i (\nabla \cdot \mathbf{u}) + \rho \left(\frac{\partial u_i}{\partial t} + \mathbf{u} \cdot \nabla u_i \right)$$

note LHS = $\frac{\partial \rho}{\partial t} u_i + \frac{\partial u_i}{\partial t} \rho + \nabla u_i \cdot (\rho \mathbf{u}) + u_i \nabla \cdot (\rho \mathbf{u})$

$$= u_i \left\{ \underbrace{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u})}_{=0} \right\} + \rho \underbrace{\left(\frac{\partial u_i}{\partial t} + \mathbf{u} \cdot \nabla u_i \right)}_{\frac{Du_i}{Dt}}$$

$$\therefore \rho \frac{Du_i}{Dt} = -\nabla p + \rho g_i + \mu \nabla^2 u_i$$

$$\therefore \mathbf{g} = [g \sin \alpha, g \cos \alpha]$$

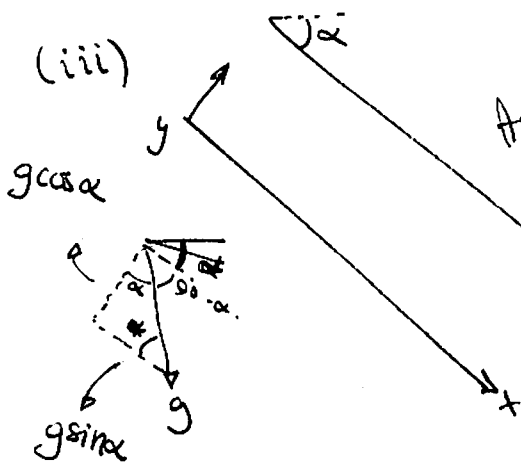
Assume uni-directional $\Rightarrow \mathbf{u} = [u(y), 0]$ $\frac{\partial}{\partial x} = 0$

$$\therefore \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -p_x + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$v \frac{\partial u}{\partial x} + \frac{\partial u}{\partial t} + v \frac{\partial u}{\partial y} = -p_y + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + g \cos \alpha$$

$$\therefore p_y = \rho g \cos \alpha$$

$$\Rightarrow p = (\rho g \cos \alpha) y + f(x)$$



$$\therefore p_x = f'(x) \text{ and } p_x = \mu u_{yy} + \rho g \sin \alpha$$

$$\Rightarrow \underbrace{\mu u_{yy}}_{\text{fn. of } y} = \underbrace{p_x - \rho g \sin \alpha}_{\text{fn. of } x}$$

$$\therefore \mu u_{yy} = -G - g \sin \alpha = -(\rho g \sin \alpha + G) \text{ where}$$

$$G = -p_x = \text{const.}$$

B.C.s? Bottom plate stat $\Rightarrow u(0) = 0$.

Top plate moves with fluid.

Stress on top $\Rightarrow F_i = \sigma_{ij} n_j = \sigma_{i2} n_2$

$$\sigma_{i2} = \mu \left(\frac{\partial u_i}{\partial x_2} + \frac{\partial u_2}{\partial x_i} \right) - \rho \delta_{i2}$$



$$n = [0, -1]$$

only element is $\sigma_{12} = \mu \frac{\partial u}{\partial y}(h)$

$$\therefore \text{shear stresses. } -\mu \frac{\partial u}{\partial y}(h) = \tau \quad (\text{why take normal into fluid?})$$

Then $\mu u_{yy} = -(\rho g \sin \alpha + G)$

$$\Rightarrow \mu u_y = -(\rho g \sin \alpha + G)y + \text{const.}$$

$$\text{@ } y=h \Rightarrow \tau = -(\rho g \sin \alpha + G)h + C$$

$$\therefore \mu u_y = -(\rho g \sin \alpha + G)y + \tau + (\rho g \sin \alpha + G)h$$

$$\mu u_y = (\rho g \sin \alpha + G)(h-y) + \tau$$

$$\Rightarrow \mu u = (\rho g \sin \alpha + G)(hy - \frac{1}{2}y^2) + \tau y + D$$

$$u(0) = 0 \Rightarrow D = 0$$

~~$$\Rightarrow \mu u = (\rho g \sin \alpha + G)(hy - \frac{1}{2}y^2) + \tau y$$~~

Then using $u = U$ on $y = h$

$$\Rightarrow \mu U = \tau h + (\rho g \sin \alpha + G)h^2 \left(1 - \frac{1}{2}\right)$$

Then...

$$u = \frac{1}{\mu} \left\{ \frac{\tau}{h} + G + \rho g \sin \alpha \right\} h y - \frac{1}{2\mu} (G + \rho g \sin \alpha) y^2$$

$$= \beta y (h - y) g \sin \alpha.$$

Moreover, the shear stress at the lower plate is.

$$\sigma_{12} \Big|_{y=0} = \mu \cdot \frac{\partial u}{\partial y} (0)$$

$$= \underline{\underline{(\rho g \sin \alpha + G) h + \tau}}$$

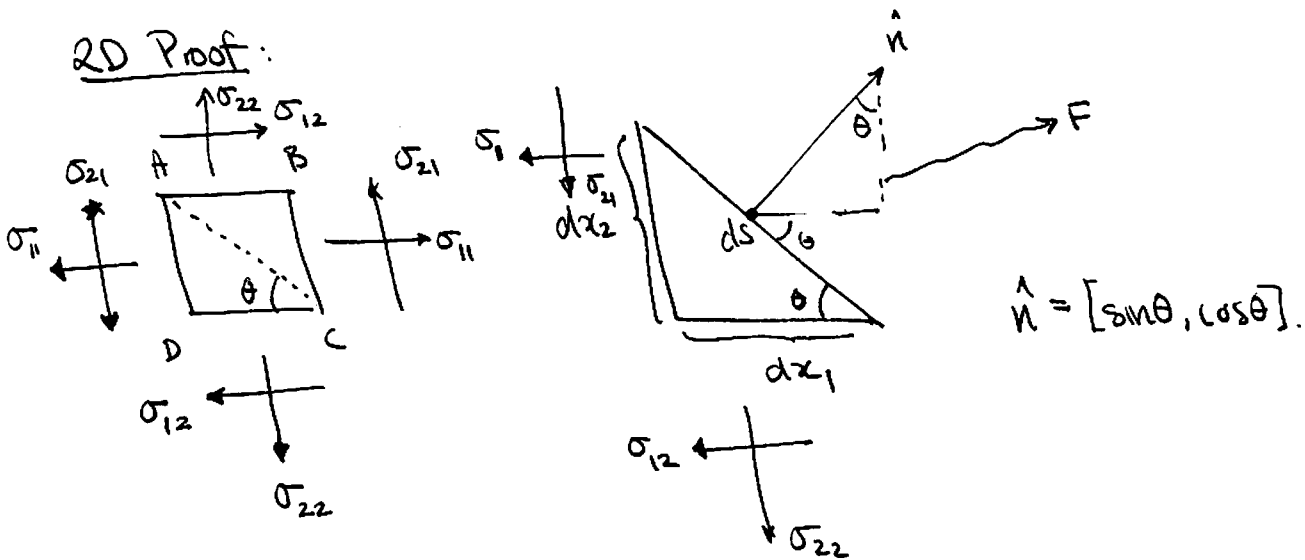
2007

#1 Remember: Stress vector \mathbf{T} : Force per area on surface element with normal \hat{n} by fluid.

Stress tensor σ_{ij} : Force per unit area in i^{th} direction on surface with normal e_j .

Cauchy's Stress Thm.: $T_i(\hat{n}) = \sigma_{ij} n_j$

2D Proof:



Consider force on point with element ds . By force balance.

$$ds \cdot \mathbf{T}_1 = \sigma_{12} dx_1 + \sigma_{21} dx_2$$

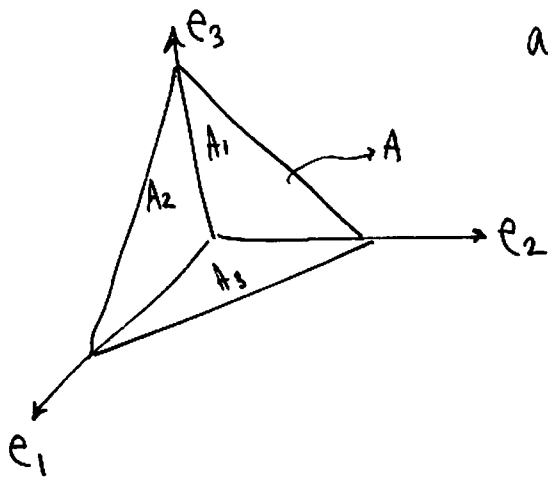
$$\Rightarrow \mathbf{T}_1 = \sigma_{12} \frac{dx_1}{ds} + \sigma_{21} \frac{dx_2}{ds}$$

$$= \sigma_{12} \cdot \underset{\uparrow n_2}{\cos\theta} + \sigma_{21} \cdot \underset{\uparrow n_1}{\sin\theta}$$

$$\mathbf{T}_1 = \sigma_{ij} n_j \quad \text{and similarly for } \mathbf{T}_2$$

(Technically, we should have used θ_1, θ_2 and $\theta_1 \neq \theta_2$)

Essentially the same in 3-D:



assume area of $A \sim L^2$.

By Newton's Law:

$$\underbrace{\iiint_V \rho \cdot \frac{D\mathbf{u}}{Dt} - \rho \mathbf{F} dV}_{O(L^3) \text{ by MVT.}} = \iint_{\partial V} \boldsymbol{\tau} \cdot d\mathbf{s}.$$

\therefore We have force balance over the faces:

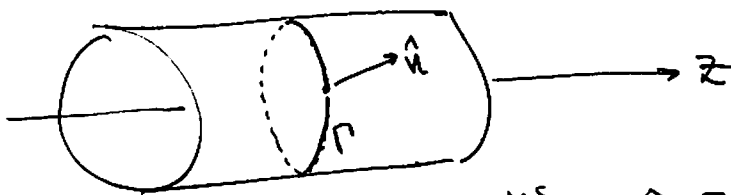
$$\boldsymbol{\tau}_i(\hat{n}) \cdot L^2 + \boldsymbol{\tau}(-\mathbf{e}_j) \cdot L^2 \cdot n_j = O(L^3) \text{ as } L \rightarrow 0.$$

$$\Rightarrow \boldsymbol{\tau}_i(\hat{n}) L^2 = \boldsymbol{\tau}(\mathbf{e}_j) n_j \cdot L^2 \text{ as } L \rightarrow 0$$

$$\therefore \text{ need } \boldsymbol{\tau}_i(\hat{n}) = \underbrace{\boldsymbol{\tau}(\mathbf{e}_j)}_{\sigma_{ij}} n_j = \sigma_{ij} n_j$$

□

Proof of momentum + NS eqns are the same.



Axi-symmetric:
 $\mathbf{u} = [0, 0, w(x, y)]$

$$\text{NS: } \begin{aligned} 0 &= -p_x \\ 0 &= -p_y \\ 0 &= -p_z + \mu(w_{xx} + w_{yy}) \end{aligned}$$

$$\Rightarrow \mu \nabla^2 w = p_z = \text{const.}$$

$$\text{Drag} = - \int_{\Gamma} \tau_3 \cdot d\mathbf{s} = - \int_{\Gamma} \sigma_{31} n_1 + \sigma_{32} n_2 \cdot d\mathbf{s}.$$

(assuming outward normal from exterior)

note $\sigma_{31} = \mu w_x, \sigma_{32} = \mu w_y$

$$\Rightarrow D = - \int_{\Gamma} \mu \nabla w \cdot \hat{n} \cdot d\mathbf{s} = - \iiint_V \mu \nabla^2 w \cdot dV = -p_z \cdot A$$

note negative sign is force from wall on fluid. It would be positive force on wall from fluid.

2006

#4 Deriving the energy eqn:

Assuming c_v & k are constant...

$$\underbrace{\frac{d}{dt} \iiint_{V(t)} \rho c_v T + \frac{1}{2} \rho u_i^2 \cdot dV}_{\text{change in internal n.erg.}} = \underbrace{\iint_{\partial V} \mathbf{q} \cdot (-\mathbf{n}) \cdot dS}_{\text{r.o. heat flux into } V(t)} + \underbrace{\iint_{\partial V} \boldsymbol{\tau} \cdot \mathbf{u} \cdot dS}_{\text{r.o. work done by surface stresses on } V(t)} + \underbrace{\iiint_{V(t)} \rho \mathbf{F} \cdot \mathbf{u} \cdot dV}_{\text{body forces}}$$

$\sigma_{ij} u_j u_i = (\sigma_{ij} u_i) n_j$

By Fourier's Law:

$$\iint_{\partial V} -k \nabla T \cdot (-\mathbf{n}) \cdot dS$$

$$\therefore \frac{d}{dt} \iiint_{V(t)} \rho c_v T + \frac{1}{2} \rho u_i^2 \cdot dV = \iiint_{V(t)} \frac{\partial}{\partial x_j} \left(k \frac{\partial T}{\partial x_j} \right) + \frac{\partial}{\partial x_j} (\sigma_{ij} u_i) + \rho F_i u_i \cdot dV$$

note $\frac{d}{dt} \iiint_{V(t)} (\rho f) \cdot dV = \rho \iiint_{V(t)} \frac{Df}{Dt} \cdot dV$ if incompressible.

$$\therefore \rho c_v \cdot \frac{DT}{Dt} + u_i \left(\rho \frac{D u_i}{Dt} - \frac{\partial}{\partial x_j} \sigma_{ij} - \rho F_i \right) = k \nabla^2 T + \underbrace{\sigma_{ij} \frac{\partial u_i}{\partial x_j}}_{\Phi}$$

\nearrow opps x

$$\therefore \rho c_v \cdot \frac{DT}{Dt} = k \nabla^2 T + \Phi.$$

Note $\Phi = \sigma_{ij} \frac{\partial u_i}{\partial x_j} = \left(-p \delta_{ij} + \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right) \frac{\partial u_i}{\partial x_j}$

write $e_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \Rightarrow \Phi = 2\mu e_{ij} \frac{\partial u_i}{\partial x_j}$

$$\begin{aligned} \text{Then } \underline{Q} &= \mu e_{ij} \frac{\partial u_i}{\partial x_j} + \mu e_{ji} \frac{\partial u_j}{\partial x_i} \\ &= \mu e_{ij} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad \text{using } e_{ij} = e_{ji} \\ &= \frac{\mu}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)^2 \end{aligned}$$

$$T = T_0$$

$$\text{////////// } y = h \quad \underline{u} = \left[\frac{Uy}{h}, 0 \right]$$

$$\text{////////// } y = 0 \quad \text{assume } T = T(y)$$

$$T = T_0$$

$$\text{Then } \rho c_v \left(\frac{\partial T}{\partial t} + u_i \frac{\partial T}{\partial x_i} \right) = k \nabla^2 T + \frac{\mu}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)^2$$

$$\Rightarrow \rho c_v (T_t) = k T_{yy} + \frac{\mu}{2} \left(\frac{\partial u}{\partial y} \right)^2$$

$$\rho c_v T_t = k T_{yy} + \frac{\mu U^2}{h^2}$$

Steady-state:

$$T_{yy} = -\frac{\mu U^2}{k h^2} \Rightarrow T = T_0 + \frac{\mu U^2}{k h^2} (h-y)y$$

Time dependent? write $T = \bar{T} + T_1$ with $T(y, t) = T_1$ @ $y=0, h$
 $\Rightarrow \bar{T}(0, h, t) = T_0$

$$\left[\begin{array}{l} T = \bar{T} + T_1 \\ + \frac{\mu U^2}{k h^2} y(h-y) \end{array} \right]$$

Then:

$$\rho c_v \bar{T}_t = k \bar{T}_{yy}$$

$$\begin{aligned} \Rightarrow \text{write } \bar{T} = f(t)g(y) &\Rightarrow \rho c_v f'g = k f g'' \\ &\Rightarrow \frac{f'}{f} = \frac{k}{\rho c_v} \frac{g''}{g} = -\lambda \end{aligned}$$

Clean-up:

$$\text{Write } T(y, t) = \bar{T} + T_1 + \frac{\mu U^2}{k h^2} y(h-y)$$

$$T(y, 0) = T_s \Rightarrow \bar{T}(y, 0) = T_0 - T_1$$

$$\left. \begin{array}{l} T(0, t) = T_1 \\ T(h, t) = T_1 \end{array} \right\} \Rightarrow \bar{T}(0, t) = 0 = \bar{T}(h, t)$$

$$\therefore \rho c_v \bar{T}_t = k \bar{T}_{yy}$$

$$\text{Let } \bar{T} = f(t)g(y) \Rightarrow \frac{f'}{f} \frac{\rho c_v}{k} = \frac{g''}{g} = -\lambda^2$$

$$\therefore f = C e^{-\lambda^2 \frac{\rho c_v}{k} t}$$

$$\text{Also: } g'' = -\lambda^2 g \Rightarrow g = D \cos \lambda y + E \sin \lambda y$$

$$g(0) = 0 \Rightarrow D = 0$$

$$g(h) = 0 \Rightarrow \lambda h = n\pi \Rightarrow \lambda = \frac{n\pi}{h}$$

$$\therefore \bar{T} = \sum_{n=1}^{\infty} a_n \sin\left(\frac{n\pi}{h} y\right) e^{-\frac{n^2 \pi^2}{h^2} \frac{\rho c_v}{k} t}$$

$$\text{Apply } \bar{T}(y, 0) = T_0 - T_1 \Rightarrow T_0 - T_1 = \sum_{n=1}^{\infty} a_n \sin\left(\frac{n\pi}{h} y\right)$$

$$\therefore a_n = \frac{2}{h} \int_0^h \sin\left(\frac{n\pi}{h} y\right) (T_0 - T_1) dy$$

$$= \frac{2(T_0 - T_1)}{h\pi} \left[(-1)^n + 1 \right]$$

$$\therefore a_{2n} = 0 \quad ; \quad a_{2n+1} = \frac{4(T_0 - T_1)}{(2n+1)\pi}$$

$$\therefore T(y, t) = T_c + \frac{\mu \bar{U}^2}{kh^2} y(h-y) + \sum_{n=1}^{\infty} \frac{4(T_0 - T_c)}{(2n+1)\pi} \sin\left[\frac{(2n+1)\pi}{h} y\right] \times e^{-\frac{k}{\rho c h^2} (2n+1)^2 \pi^2 t}.$$

If the boundary is insulated \textcircled{a} $t=0$

$$\Rightarrow T_y(0, 0) = 0 \quad \& \quad T_y(h, 0) = 0.$$

$$k \cdot T_{yy} = \frac{\mu \bar{U}^2}{h^2} \Rightarrow T_y = \frac{\mu \bar{U}^2}{kh^2} y + C \quad \begin{matrix} \uparrow \\ = 0 \end{matrix}$$

no way to satisfy both \therefore no steady sol'n.

To solve with these conditions, seek "steady sol'n" in $T = T(t)$

$$\begin{aligned} \therefore \rho c v \bar{T}_t &= \frac{\mu \bar{U}^2}{h^2} \Rightarrow T = C e^{\frac{\mu \bar{U}^2}{h^2 \rho c v} t} \\ &\Rightarrow T_y \equiv 0 \text{ for arbitrary } C. \end{aligned}$$

WLOG, set $C=1$ and linearise around this sol'n.

$$\text{Let } T = e^{\frac{\mu \bar{U}^2}{h^2 \rho c v} t} + \bar{T} \Rightarrow \rho c v \cdot \bar{T}_t = k \bar{T}_{yy}.$$

now separate and solve subject to $\bar{T}_y = 0$ on $y=0, h$.

$$T = T_1 + \frac{\mu U^2}{2kh^2} y(h-y) + \Theta$$

$$\Theta = 0 \quad y = 0, h,$$

$$\Theta = T_0 - T_1 \quad \text{on } t = 0$$

$$\Theta = \sum_1 a_n \sin\left(\frac{n\pi y}{h}\right) e^{-\frac{k n^2 \pi^2 t}{\rho c h^2}}$$

$$T_0 - T_1 = \sum_1 \sin\left(\frac{n\pi y}{h}\right) \cdot a_n \quad \text{in } 0 < y < h$$

$$\begin{aligned} \Rightarrow a_n &= \frac{2}{h} \int_0^h (T_0 - T_1) \sin \frac{n\pi y}{h} dy \\ &= \frac{2(T_0 - T_1)}{n\pi} \left\{ (-1)^{n+1} + 1 \right\} \end{aligned}$$

$$a_{2n} = 0 \quad a_{2n+1} = \frac{4(T_0 - T_1)}{(2n+1)\pi}$$

Insulated walls: $T_y = 0$ on $y = 0, h$
no sol'n to steady state.

But $T = \frac{\mu U^2}{e^{c k t}} t$ satisfies eqn for T .

\therefore write $T = \frac{\mu U^2}{e^{c k t}} t + \Theta$

$$\Rightarrow \rho c \Theta_t = k \Theta_{yy} \quad \Theta_y = 0 \quad \text{on } y = 0, h$$

$$\Theta = T_0 + \frac{\mu U^2}{2kh^2} y(h-y) \quad \text{on } t = 0$$

Separate to get

$$\Theta = \sum b_n \cos\left(\frac{n\pi y}{h}\right) e^{-\frac{k n^2 \pi^2 t}{\rho c h^2}}$$

#1 Width of B.L. is... $\gamma \sim \alpha(e^{-\alpha(x)})$.

increases if $\alpha < 0$ i.e. $U' < 0$. decelerating.
decreases if $\alpha > 0$ i.e. $U' > 0$. accelerating.

This trend is true for general flows.

\Rightarrow acc. flows make B.L. thin.

dec. flows make B.L. thick

but switch (increasing to decreasing) doesn't
always happen at switch from dec. to acc.

In particular, unif. flow has $\gamma \sim x^{1/2}$ and
 $U = x^\alpha \Rightarrow$ switch from growth to decay occurs

② $\alpha = 1$

B.L. remains attached if $p' > 0$. Detached if $p' < 0$
and in this case ($\alpha < 0$), B.L. theory breaks down.

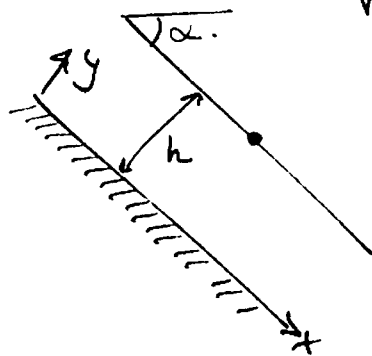
2005

#1 Same as 2008 except...

What are assumptions of Newtonian fluid?

- (A) T_{ij} is linear relation of velocity gradients
- (B) T_{ij} is invariant to rotations (isotropic)
e.g. stress tensor is symmetric.

Flow problem



has free surface :

need extra condition

(i) Kinematic

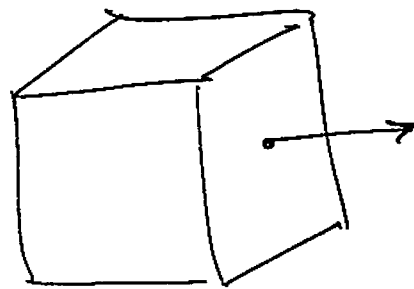
$$\frac{D}{Dt}(y-v) = 0$$

automatic.

(ii) Dynamic

$$\frac{\partial u}{\partial y} \Big|_{y=h} = 0.$$

$$\tau_i = \sigma_{ij} n_j$$



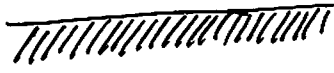
2004

#1. First part is standard.

$u=0$.

Assume that $\underline{u} = [u(y), 0]$.

Then clearly:



$$u = U \cos \omega t$$

$$\rho u_t = \mu u_{yy}$$

$$\text{Write: } u = f(y) e^{i\omega t} \Rightarrow \rho i\omega \cdot f = \mu f''$$

$$\Rightarrow r^2 = \frac{\rho i\omega}{\mu}$$

$$\Rightarrow r = \underbrace{\sqrt{\frac{\rho\omega}{2\mu}}}_{k} (1+i)$$

$$f(y) = \underbrace{A e^{k(1+i)y}}_{\text{kill this mode}} + B e^{-k(1+i)y}$$

kill this mode \Rightarrow need decay.

$$\therefore f(y) = B e^{-k(1+i)y} \quad \text{Need } f(0) = U \Rightarrow B = U$$

$$\begin{aligned} \text{Then } u(y) &= U e^{-k(1+i)y} e^{i\omega t} \\ &= U e^{-ky} e^{i(\omega t - ky)} \end{aligned}$$

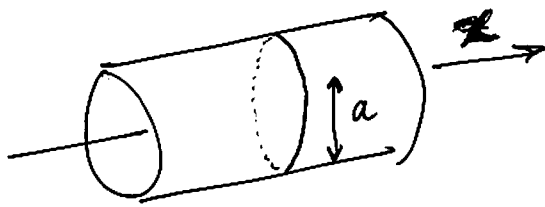
$$\therefore \Re(\dots) = U e^{-ky} \cos(\omega t - ky)$$

$$= U e^{-\sqrt{\frac{\rho\omega}{2\mu}} y} \cos\left(\sqrt{\frac{\rho\omega}{2\mu}} y - \omega t\right)$$



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#1 First part is standard.



$$\text{Let } \underline{u} = [u(x, y), 0, 0].$$

$$\text{We have } \mu(u_{yy} + u_{zz}) = p_x = -G$$

Transform to cylindrical coords.

$$\nabla^2 u = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{\partial^2 u}{\partial z^2}$$

$$\text{Let } u(z, y) = u(r)$$

$$\therefore \mu \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = -G$$

$$\Rightarrow \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = -\frac{Gr}{\mu}$$

$$r \frac{\partial u}{\partial r} = -\frac{Gr^2}{2\mu} + C$$

$$\frac{\partial u}{\partial r} = -\frac{Gr}{2\mu} + \frac{C}{r} \quad \text{bounded}$$

$$\Rightarrow u = -\frac{Gr^2}{4\mu} + C \log r + D$$

$$u(a) = 0 \Rightarrow D = \frac{Ga^2}{4\mu} \Rightarrow u = \frac{G}{4\mu} (a^2 - r^2)$$

$$\text{Flux: } Q = \int_0^{2\pi} \int_0^a u \cdot r \cdot dr \cdot d\theta = 2\pi \int_0^a \frac{G}{4\mu} (a^2 r - r^3) \cdot dr$$

$$= \frac{G\pi}{2\mu} \left(\frac{a^2}{2} a^2 - \frac{1}{4} a^4 \right) = \frac{G\pi a^4}{8\mu}$$

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#4

$$g u_t = \mu u_{yy}$$

$$u = U \cos \omega t \quad \text{on } y=0 \quad u=0 \quad \text{on } y=h.$$

$$\text{Let } u = f(y) e^{i\omega t} \quad \alpha = (1+i) \sqrt{\frac{g\omega}{2\mu}}$$

$$\begin{aligned} \therefore f &= A e^{\alpha y} + B e^{-\alpha y} \\ U &= A + B \\ 0 &= A e^{\alpha h} + B e^{-\alpha h} \end{aligned} \Rightarrow \begin{aligned} A &= \frac{-U e^{-\alpha h}}{2 \sinh \alpha h} \\ B &= \frac{U e^{\alpha h}}{2 \sinh \alpha h} \end{aligned}$$

$$u = \text{Re} \left\{ \frac{U \sinh \alpha (h-y) e^{i\omega t}}{\sinh \alpha h} \right\}$$

$$P = \text{force on plane} = \mu \frac{\partial u}{\partial y} \Big|_{y=0} = \text{Re} \left[-\mu U \alpha \coth \alpha h e^{i\omega t} \right]$$

$$h \rightarrow \infty \Rightarrow P \rightarrow \text{Re} \left[-\mu U (1+i) \sqrt{\frac{g\omega}{2\mu}} (\cos \omega t + i \sin \omega t) \right]$$

$$\begin{aligned} P &\sim \sigma \sqrt{g\omega\mu} \frac{i}{\sqrt{2}} (-\cos \omega t + i \sin \omega t) \\ &= \sigma \sqrt{g\omega\mu} \sin(\omega t - \pi/4) \end{aligned}$$

#1 $\frac{d}{dy}(\mu u_y) = 0 \quad kT_{yy} + \mu(u_y)' = 0.$

$\Rightarrow \mu u_y = C = \tau_w$ after having applied B.C.s.

$\therefore kT_{yy} + \frac{\tau_w^2}{\mu} = 0$

no sol'n with $T_y = 0 @ y = 0, h.$

(iv): Let $\mu = \mu_0 e^{-T}$.

$\Rightarrow kT_{yy} + \frac{\tau_w^2}{\mu_0} e^T = 0.$ with say (?)

$\alpha = \frac{\tau_w^2}{k\mu_0}$

$\Rightarrow \frac{1}{2} T_y^2 + \alpha e^T = \alpha e^{T_0}$

$T_* = 0 @ y = 1$

$T_y = 0 @ y = 0$
 $T_0 = T(0)$

$\Rightarrow \int_0^{T_0} \frac{dT}{\sqrt{e^{T_0} - e^T}} = \sqrt{2\alpha}$



need $\alpha < \alpha_*$.

#2 Last part:

(iv) Trailing edge



Can't go to $m < 0$

$\Rightarrow KJ (?)$

#3

(iii) Solve by draws.

$$\frac{dt}{1} = \frac{dx}{\frac{\rho g h^2}{\mu}} = \frac{dh}{0}$$

$$h = F\left(x - \frac{\rho g h^2}{\mu} t\right), F = h_0$$

